



Using automated camera imagery processing for surface transportation weather applications

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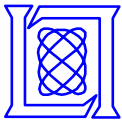
Outline

- **Current camera surveillance**
 - Usage
 - Deployments
- **Weather extraction**
 - Potential uses
 - MIT/LL Algorithm development
 - CLARUS research
- **Future possibilities**



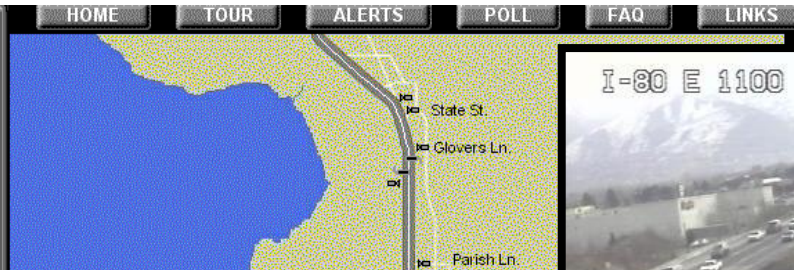
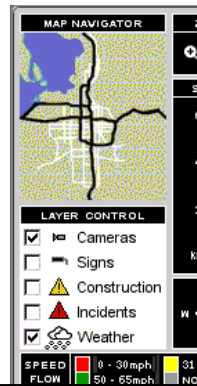
Current Camera Usage

- **Traffic surveillance**
 - Accidents/Incidents
 - Red light / Speed enforcement
 - Traffic flow
- **Security**
 - Premises monitoring
 - Intruder/Incident alerting
 - Homeland defense (terrorist threat surveillance)
- **Weather/ General condition information**
 - 511 services
 - Web based displays for commuters
 - Scenic cameras (tourism)



Example Camera Integration

Salt Lake City
Utah
150+ Cameras



mmuterlink.com 02/19/01 09:32 AM



www.utahcommuterlink.com 02/19/01 10:13 AM



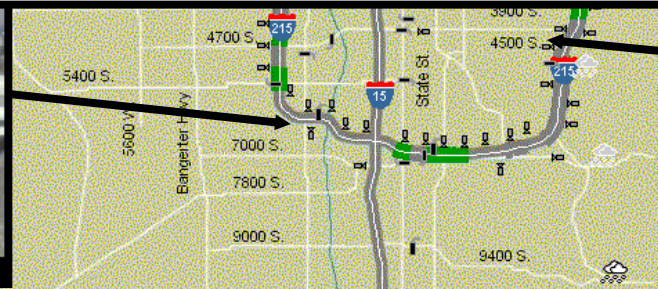
Traffic Operations Center



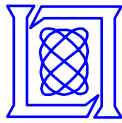
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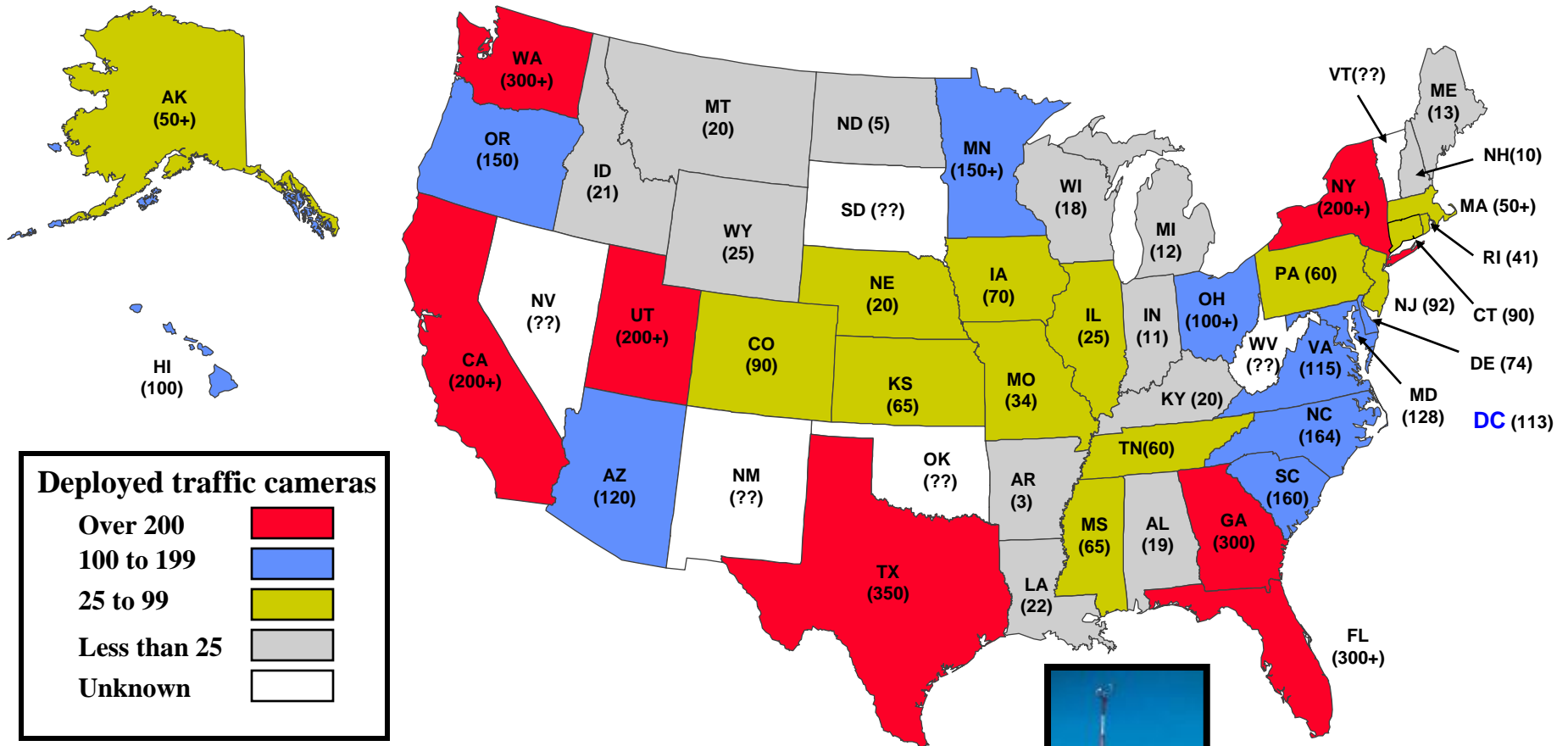
www.utahcommuterlink.com 02/19/01 10:02 AM



www.utahcommuterlink.com 02/19/01 09:31 AM



State DOT Controlled Cameras (public survey)



More than 4000 cameras

Vs. 860 ASOS Weather Stations





What's wrong with these pictures?

- Labor intensive
- Only a subset examined
- Focused on traffic incidents
- Details often lost



Real-time Traffic Cameras Rich Source of Information
- Need Automated Algorithms



Video camera observed weather variables

- Automatically measure visibility and detect fog utilizing standard visible camera imagery



Visibility: **1 km** : No Fog

Roadway Conditions:
Partially Snow Covered

Precipitation: **Moderate Snow**

Visibility(km)

>10

>5

1-5

0.0-1.0

Visibility: **0.2 km** : Heavy Fog : Thickening

Fog Description

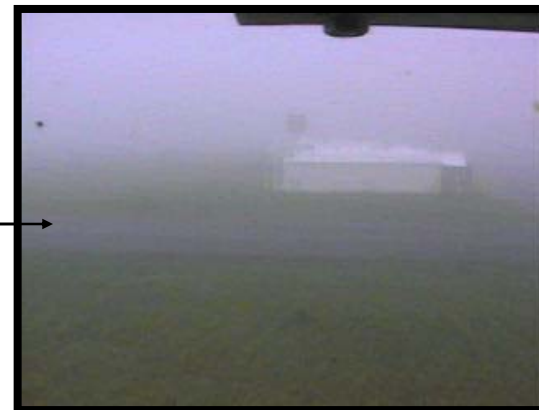
Heavy

Moderate

Light

Roadway Conditions: **Clear**

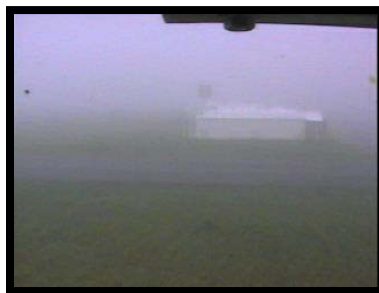
Precipitation: **None**





MIT/LL Research: Guidelines & Assumptions

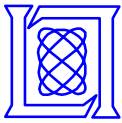
- **Keep sensor requirements simple**
 - Digital camera at known location
 - View must capture multiple ranges
 - Daylight imagery
- **Require only limited image range survey**
- **Focus on key ranges of visibility**
 - Visibility < 10km (and in particular < 1km)



Visibility(km)

>10
>5
1-5
0.0-1.0





Utilize Edge Extraction as Basis

Taconic Ridge Line: 6.7km

E-Hangar: 0.4km

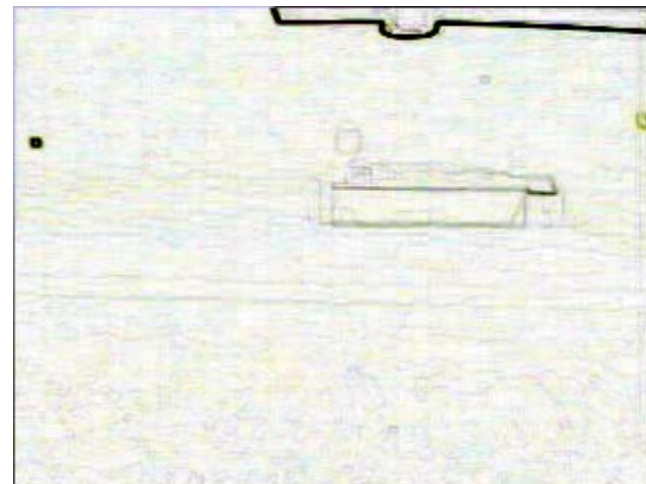
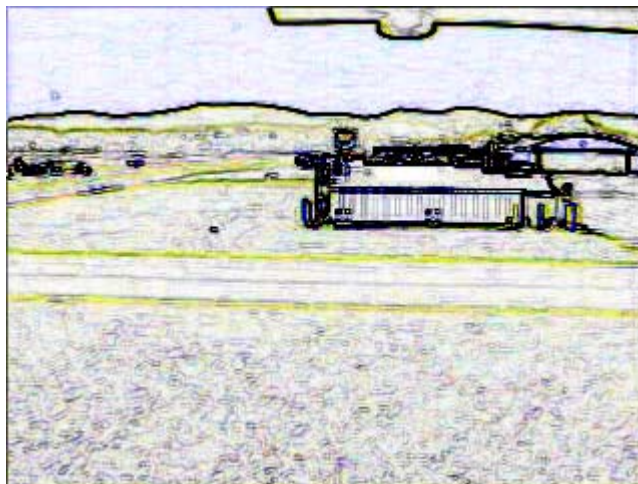
Hangar: 0.2km

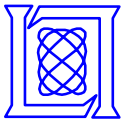


Road: 0.030km

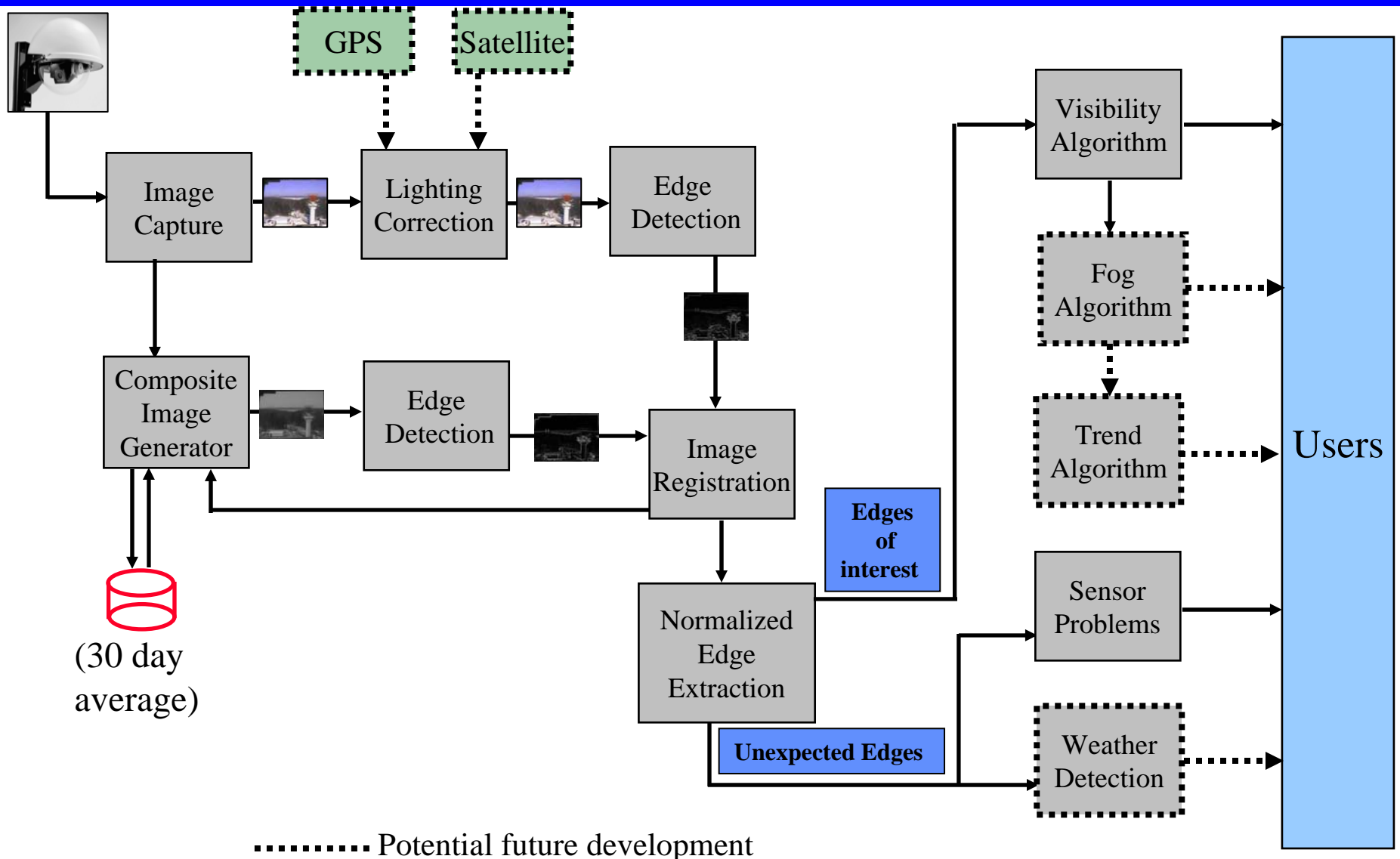
Near Ridge: 2.1km

Gas Tanks: 0.042km





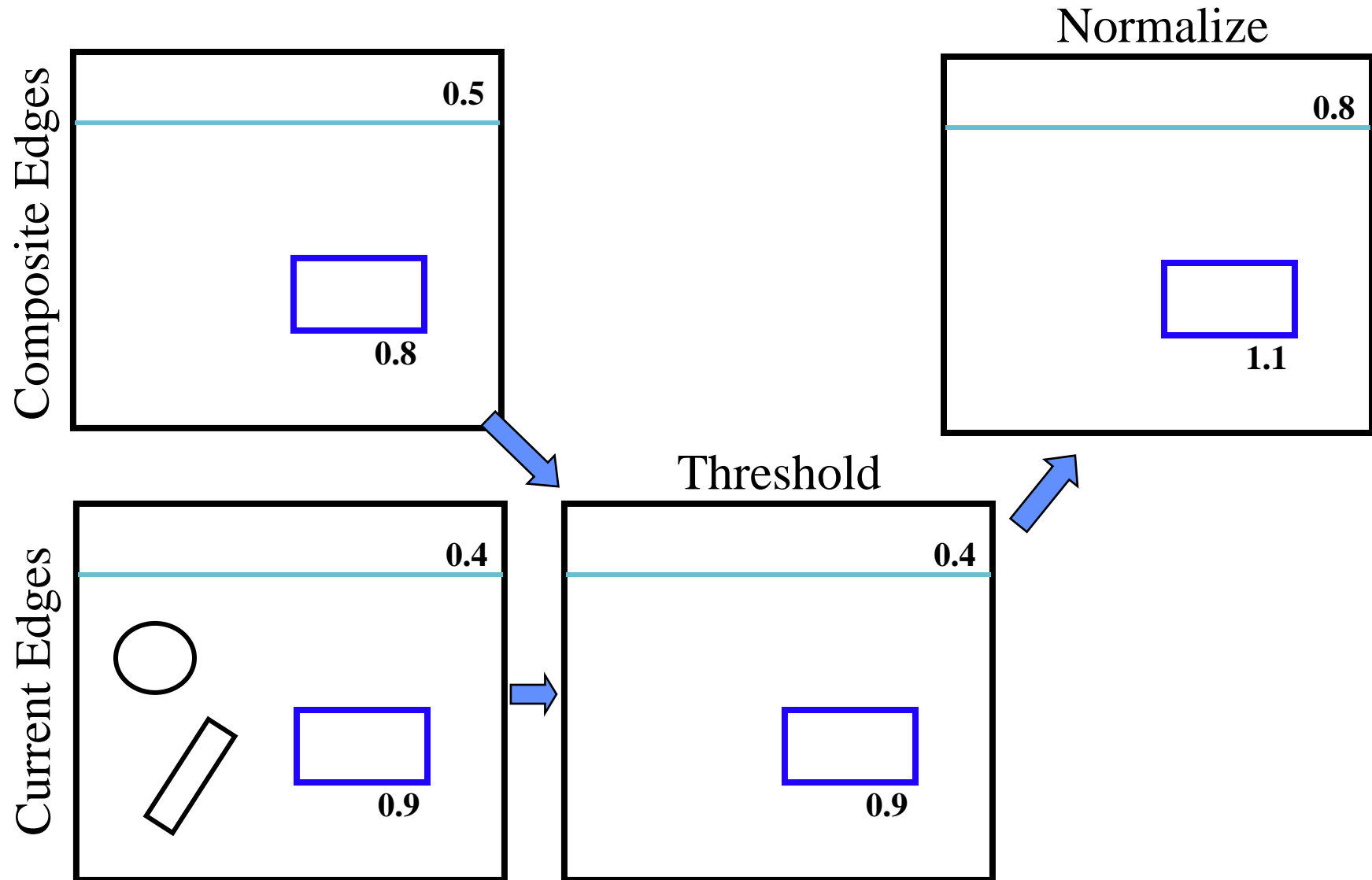
Algorithm Flow Chart

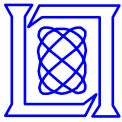


..... Potential future development

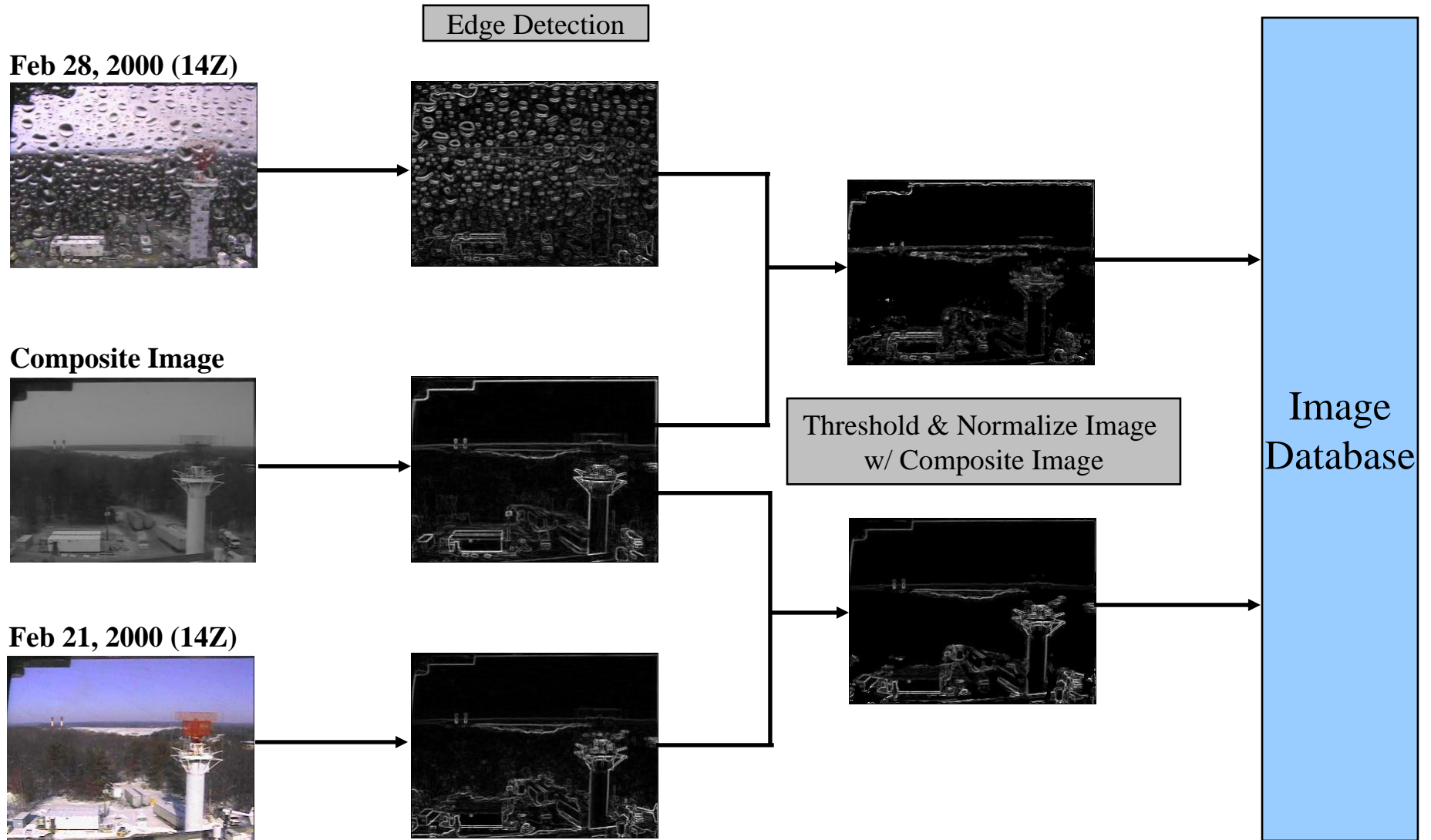


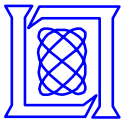
Threshold & Normalize



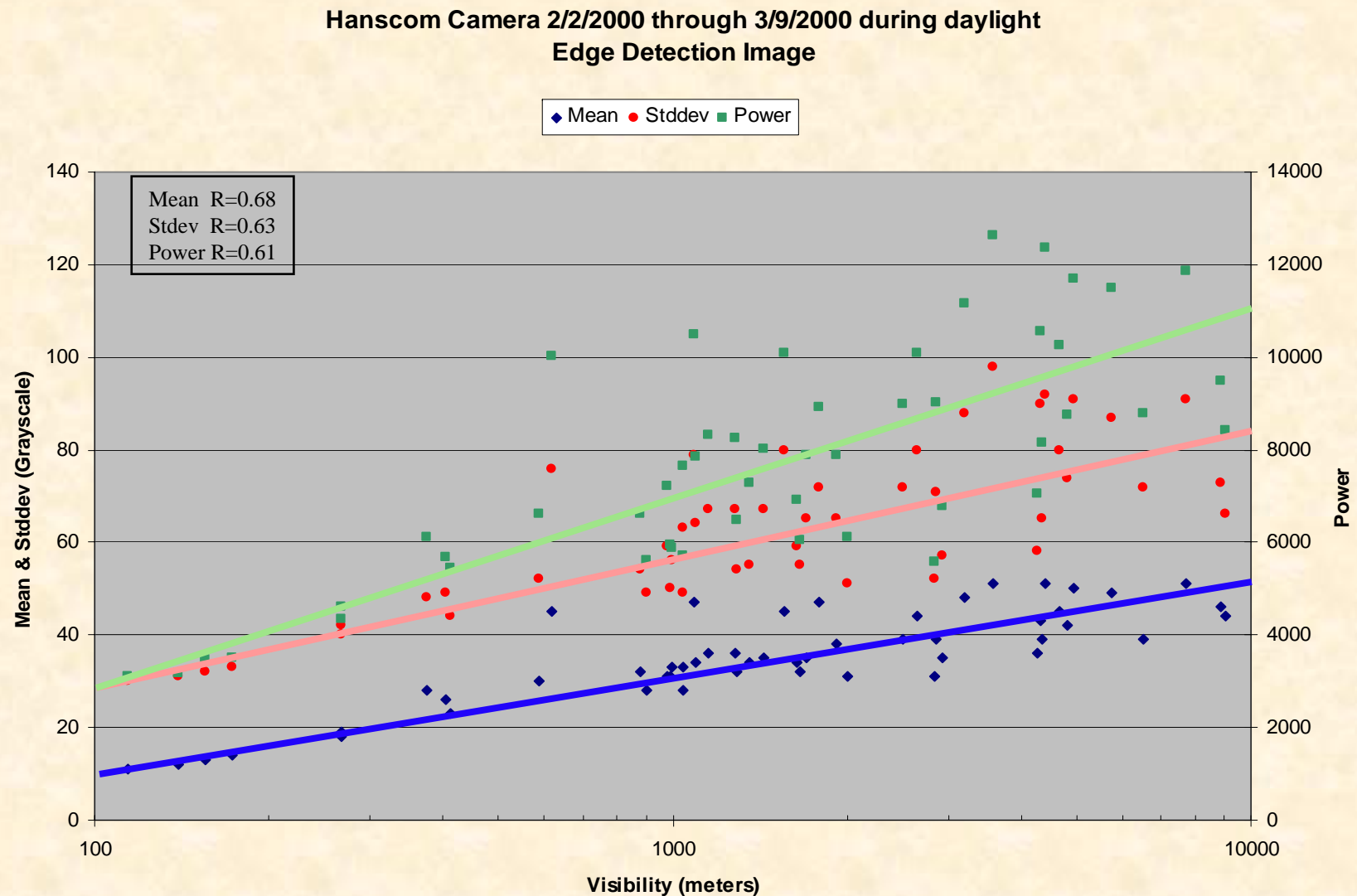


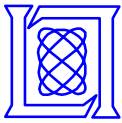
Data Quality Issues



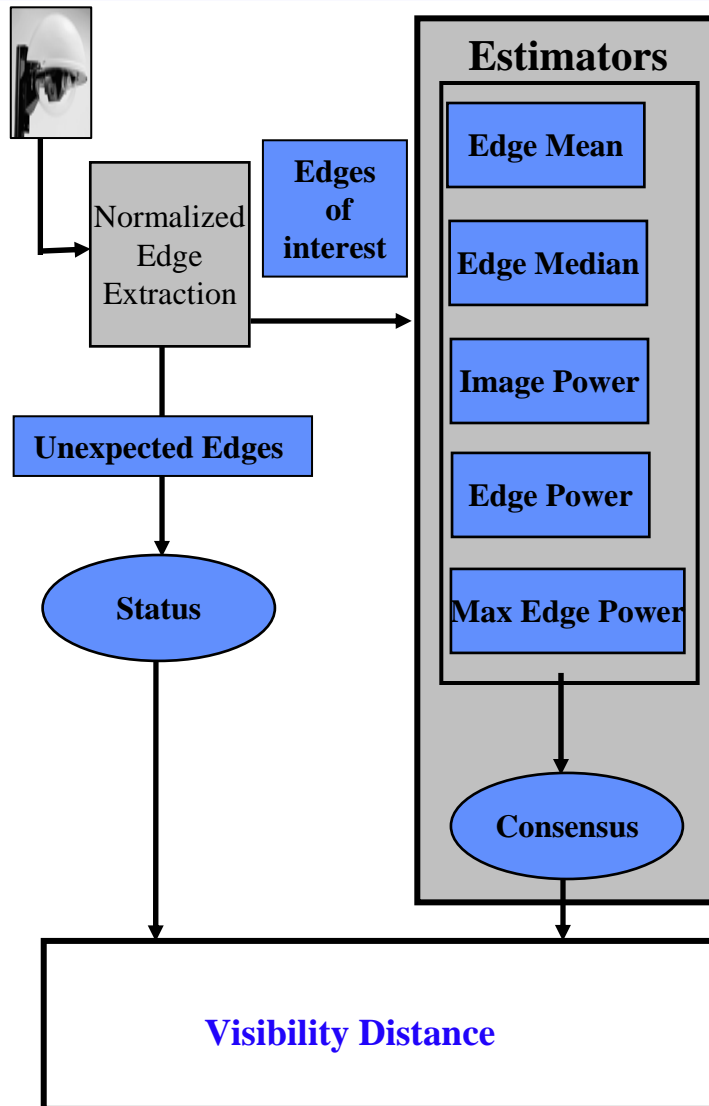


Multiple Determination Techniques





Visibility Algorithm - Initial Assessment



		Video Estimated Visibility (km)			
		<1	1-5	5-10	≥ 10
ASOS Visibility (km)	<1	28	2	0	0
	1-5	1	24	11	6
	5-10	0	10	64	32
	≥ 10	0	46	174	663

Mt. Greylock, MA hourly daylight images 7/1-10/31/00 (estimators trained on same data set)



CLARUS research: Apply algorithm generically

- Investigate current standard practice for camera imagery
- Refine algorithm at MIT/LL using off-the-shelf cameras
- Connect to multiple DOT deployed cameras to test algorithm for determining general visibility
- Funding \$250K for 1 year through 6/1/2006



02/11/2000 20Z (Vis 100 meters)



02/18/2000 20Z (Vis 1000 meters)

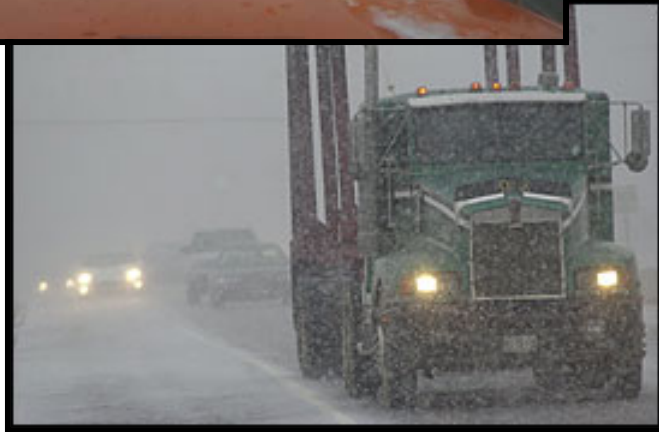


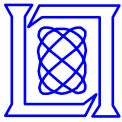
02/28/2000 17Z (Vis 10 miles)



CLARUS research: Cab-height visibility





- Utilize two-tiered MIT/LL camera system to determine feasibility of predicting cab-height visibility from elevated traffic cameras





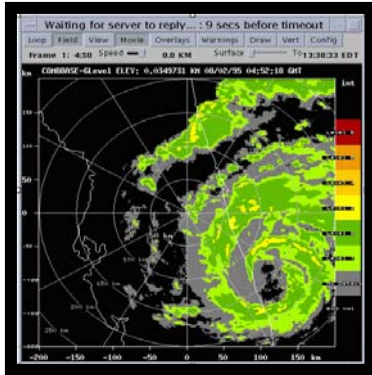
A “Vision” for Camera Usage

Image Database

Image	Attributes	Image	Attributes
	Wx: Clear, distant clouds Road: Clear Traffic: Light Camera: OK Security: Normal		Wx: Unknown Road: Unknown Traffic: Unknown Camera: Unavailable Security: Cautious
	Wx: No precip Road: Clear, snow off-road Traffic: Hvy, slow, accident Camera: OK Security: Normal		Wx: Snow Road: Snow covered Traffic: Hvy, stopped, accident Camera: OK Security: Normal



Camera Decision Support Applications



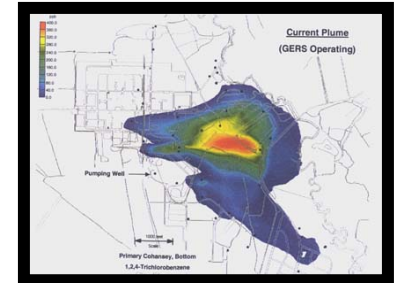
Hurricane Evacuation

- Route selection



Winter Maintenance

- Road condition feedback



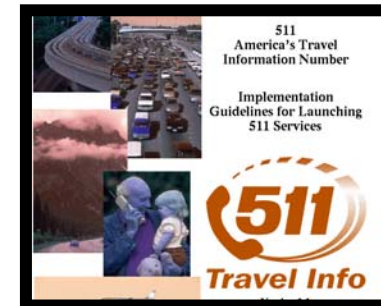
Emergency Management

- Route selection
- Threat assessment



Traffic Management

- Signal timing
- Camera view selection



511 Travel

- Travel time feedback
- Viewable routes

MIT Lincoln Laboratory



Summary

- **Camera deployments have expanded rapidly**
- **Automated techniques are needed to optimize usage**
- **Cameras provide valuable weather information**
- **MIT/LL under CLARUS is developing algorithms to extract weather variables from standard camera imagery**
 - **Estimated completion 6/1/2006**
- **Opportunities for further development**